

# Movement-Generalized Minimalist Grammars

Thomas Graf  
tgraf@ucla.edu  
tgraf.bol.ucla.edu

University of California, Los Angeles

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# Outline

- 1 Monadic Second-Order Logic (MSO)
  - Talking About Graphs
  - MSO Graph Transductions
- 2 Minimalist Grammars (MGs)
- 3 Model-Theoretic Perspective on MGs
- 4 Generalizing Move

# MSO as a Graph Description Language

- MSO = extension of FO with quantification over sets
- A set  $L$  of graphs is MSO-definable iff there is an MSO-formula  $\phi$  such that  $L$  is the set of models of  $\phi$ .
- A tree language is regular iff it is MSO-definable.

## Common Predicates

Symbol	Relation
$\triangleleft$	immediate dominance
$\triangleleft^+$	proper dominance
$\approx$	equivalence
$\sigma$	label $\sigma$

# MSO Graph Transductions

## Basic Idea

Interpret output graph as (sub)structure of the input graph

## Definition (MSO graph transduction)

A (non-copying) **MSO graph transduction**  $\tau$  consists of

- an MSO formula  $\phi$  defining the domain of the input graph,
- an MSO formula  $\psi$  defining the domain of the output graph,
- a family of MSO formulas defining the relations in the output graph in terms of the relations in the input graph.

A graph transduction from trees to trees is called an MSO tree transduction (MSO-TT).

# Examples

## Two Easy Transductions



Edge relation:  $\triangleleft$

Edge relation:  $\blacktriangleleft$

$$\tau : x \blacktriangleleft y \leftrightarrow x \triangleleft^+ y \wedge x \not\approx y$$



Edge relation:  $\triangleleft$

Edge relation:  $\blacktriangleleft$

$$\tau : x \blacktriangleleft y \leftrightarrow \exists z [x \triangleleft z \wedge y \triangleleft z]$$

$$d(x) \leftrightarrow a(x) \vee c(x)$$

$$b(x) \leftrightarrow b(x)$$

# Examples

## Two Easy Transductions



Edge relation:  $\triangleleft$

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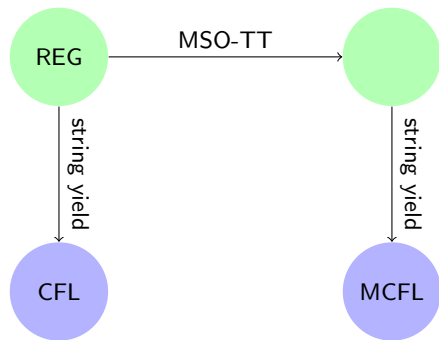
$$d(x) \leftrightarrow a(x) \vee c(x)$$

$$b(x) \leftrightarrow b(x)$$

# MSO and MCFLs

- Regular tree languages yield CFLs.
- However, the class of MCFLs is identical to the string yield of the image of the regular tree languages under MSO tree transductions (cf. Mönnich 2006).

**MCFL**  $\equiv$   
**str(MSO-TT(REG))**



# Minimalist Grammars

- Originally formulated in Stabler (1997)
- Highly lexicalized formalism inspired by Minimalist syntax (Chomsky 1995).
- Weakly equivalent to MCFGs (Harkema 2001; Michaelis 1998, 2001)
- More succinct than MCFGs (Stabler 2012)
- Derivation trees provide compact finite-state representation (Michaelis 2001; Kobele et al. 2007)
- Attractive closure properties (Graf 2011; Kobele 2011)
- Very extensible while preserving weak generative capacity



# The Atoms of a Minimalist Grammar

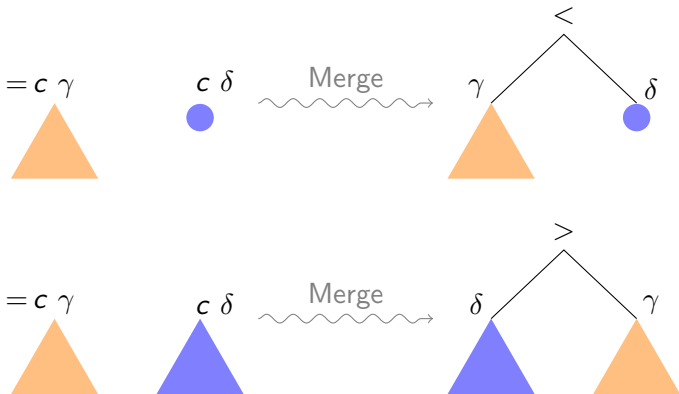
## Minimalist Grammars (Stabler 1997)

An MG is a 5-tuple  $G := \langle \Sigma, Feat, F, Lex, Op \rangle$ , where

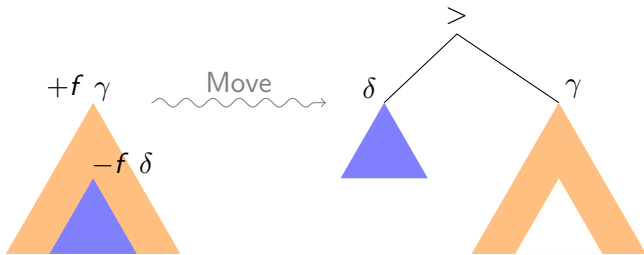
- $\Sigma$  is an alphabet,
- $Feat$  is a non-empty finite set of
  - category features  $f$ ,
  - selector features  $= f$ ,
  - movement licensee features  $-f$ ,
  - movement licensor features  $+f$ ,
- $F \subseteq Feat$  is a set of final category features,
- the lexicon  $Lex$  is a finite subset of  $\Sigma^* \times Feat^+$ ,
- $Op := \{merge, move\}$  is the set of structure-building operations.

For every MGs it suffices to specify  $Lex$  and  $F$ .

# Operation 1: Merge



# Operation 2: Move

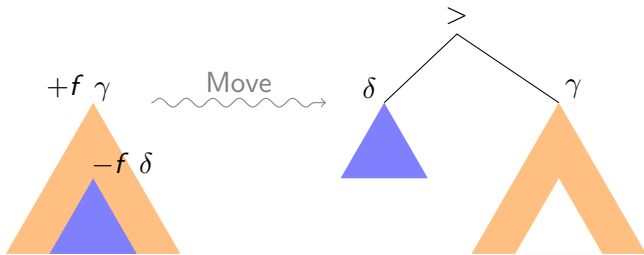


## Shortest Move Constraint (SMC)

No two lexical items may have the same licensee feature as their first unchecked feature.

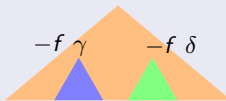


# Operation 2: Move



## Shortest Move Constraint (SMC)

No two lexical items may have the same licensee feature as their first unchecked feature.



# A Toy Example (Without Recursion)

MG with  $F = \{C\}$

men :: N

the :: =N D

which :: =N D - wh

like :: =D =D V

$\varepsilon$  :: =V C

do :: =V + wh C

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$$\frac{\text{the}}{=N D} \quad \frac{\text{men}}{N} \quad \frac{\text{like}}{=D =D V} \quad \frac{\text{which}}{=N D -wh} \quad \frac{\text{men}}{N}$$

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MG with  $F = \{C\}$

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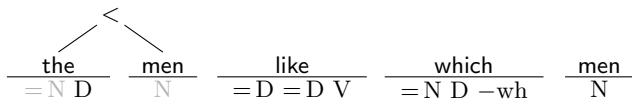
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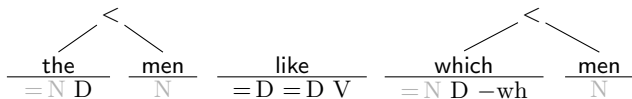
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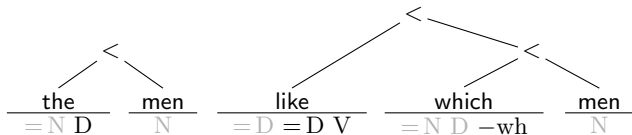
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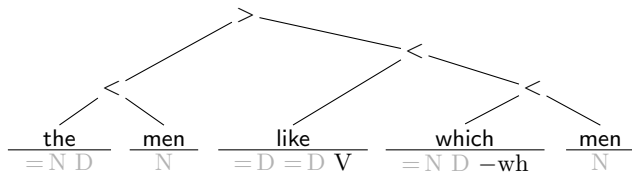
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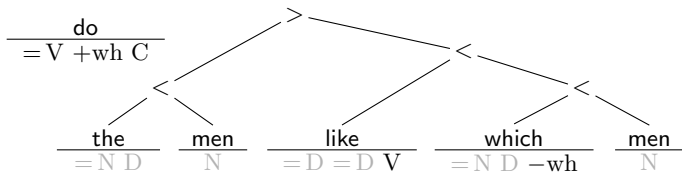
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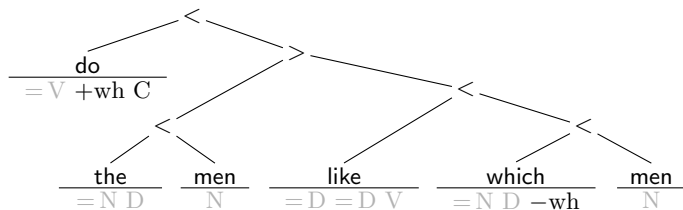
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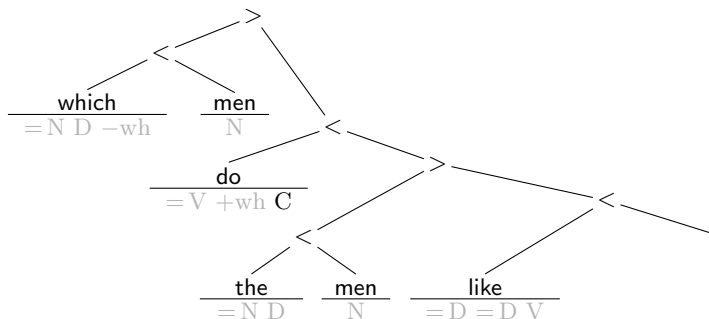
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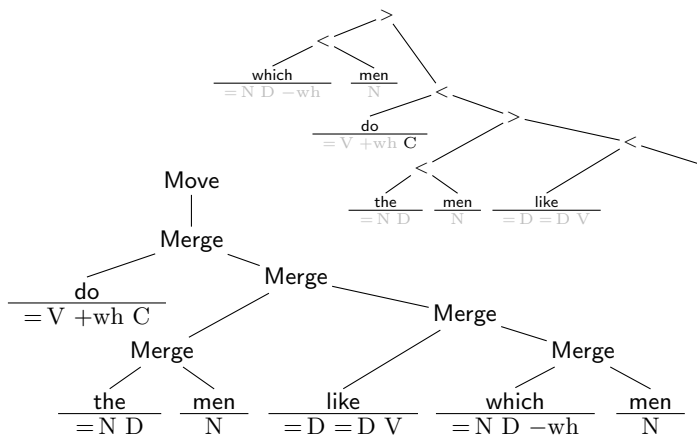
do :: =V + wh C



# A Model-Theoretic View of MGs

- Every MG is uniquely specified by its set of derivations.
- Derivations are trees  $\Rightarrow$  can be defined model-theoretically
- Each node in a derivation “belongs” to some lexical item  $\Rightarrow$  lexicon is a finite set of treelets called **slices**
- A derivation tree is a combination of slices that respects the constraints of the feature calculus.
- A given MG’s derivation tree language is the largest set of such well-formed slice combinations.
- Crucially, the constraints of the feature calculus can be **expressed in tree-geometric terms.**

# Derivation Trees



# Slices

Intuitively, slices are the **derivation tree equivalent of phrasal projection**: Each slice marks the subpart of the derivation that a lexical item has control over by virtue of its selector and licensor features.

## Slices

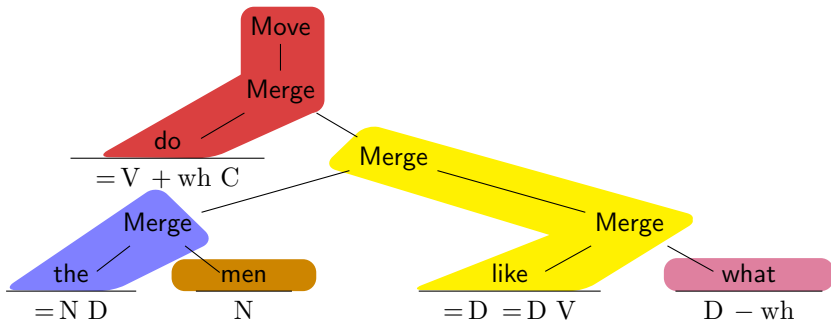
Given a derivation tree  $t$  and lexical item  $l$  occurring in  $t$ ,  $\text{slice}(l)$  is defined as follows:

- $l \in \text{slice}(l)$ ,
- if node  $n$  of  $t$  immediately dominates a node  $s \in \text{slice}(l)$ , then  $n \in \text{slice}(l)$  iff the operation denoted by the label of  $n$  erased a selector or licensor feature of  $l$ .

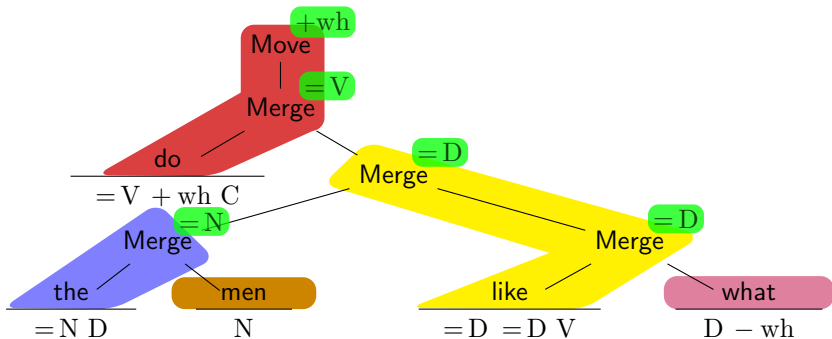
The unique  $n \in \text{slice}(l)$  that isn't (properly) dominated by any  $n' \in \text{slice}(l)$  is called the *slice root* of  $l$ .



# Example of Slices



# Example of Slices



# Regulating Merge

## Merge

If  $n$  is a Merge node associated to selector feature  $= f$ , it immediately dominates the slice root of some lexical item with category feature  $f$ .

# Regulating Move: Finding Occurrences

A Move node that checks a licensee feature of lexical item  $l$  is called an **occurrence** of  $l$ .

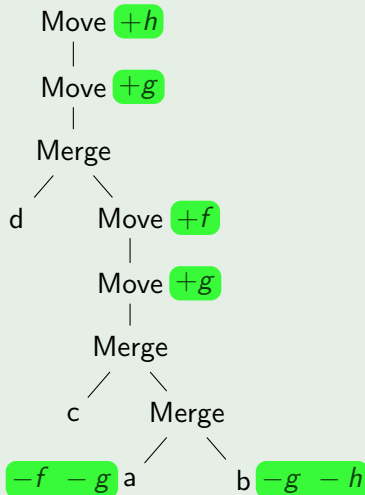
## Definition (Occurrences)

For every combination  $t$  of slices and lexical item  $l$  in  $t$  with licensee features  $-f_1 \cdots -f_n$ , the **occurrences** of  $l$  in  $t$  are:

- $occ_0(l)$  is the mother of the slice root of  $l$  in  $t$  (if it exists).
- $occ_i(l)$  is the unique node  $m$  of  $t$  labeled Move such that
  - $m$  is associated to  $+f_i$ , and
  - $m$  **properly dominates**  $occ_{i-1}$ , and
  - there is no node  $n$  in  $t$  such that
    - $n$  is associated to  $+f_i$ , and
    - $n$  properly dominates  $occ_{i-1}$ , and
    - $n$  is properly dominated by  $m$ .

# Exercise: Find the Occurrences!

## Example



# Regulating Move: Resource Sensitivity & SMC

## Move

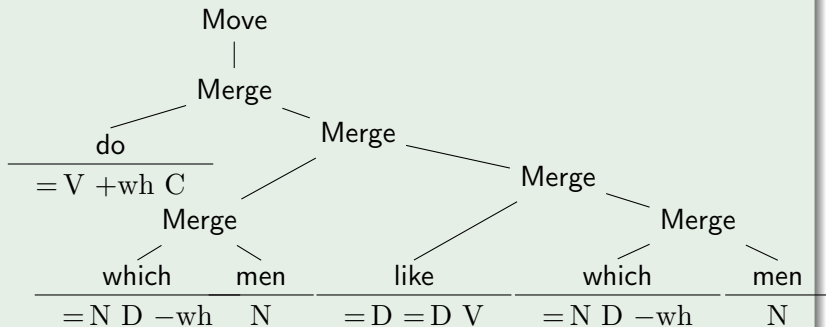
For every lexical item  $l$  with licensee features  $-f_1 \cdots -f_n$ , there exist nodes  $m_1, \dots, m_n$  such that  $m_i$  (and no other node) is the  $i$ th occurrence of  $l$ .

## SMC

For every Move node  $m$  there is exactly one lexical item  $l$  such that  $m$  is an occurrence of  $l$ .

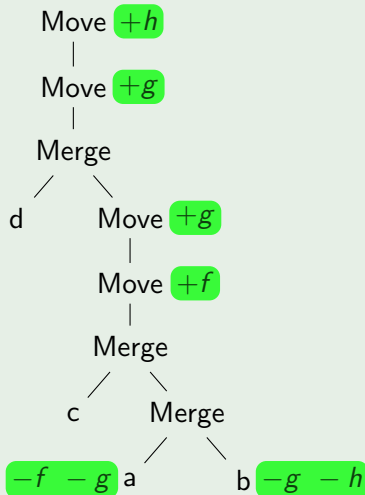
# Why the SMC Works

## Example 1



# Why the SMC Works [cont.]

## Example 2





## Mapping to Derived Trees

- Derivation trees can be mapped to derived trees by a multi bottom-up transducer (Kobele et al. 2007)
- However, an MSO tree transduction is more intuitive.
- The transduction adds a dominance branch **from an LI's highest occurrence to the root of its slice.** The original dominance branch is removed.
- Linear order and interior node labels also need to be changed. See the paper for details.

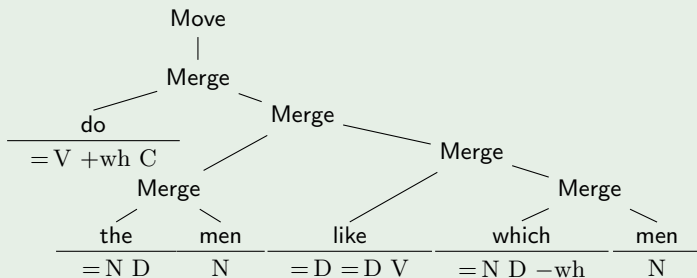
### The Transduction Formula

$$x \blacktriangleleft y \leftrightarrow x \triangleleft y \vee \exists l [f\text{-occ}(x, l) \wedge \text{ sliceroot}(y, l)]$$

$$f\text{-occ}(x, l) \leftrightarrow \text{occurrence}(x, l) \wedge \neg \exists z [z \triangleleft^+ x \wedge \text{occurrence}(z, l)]$$

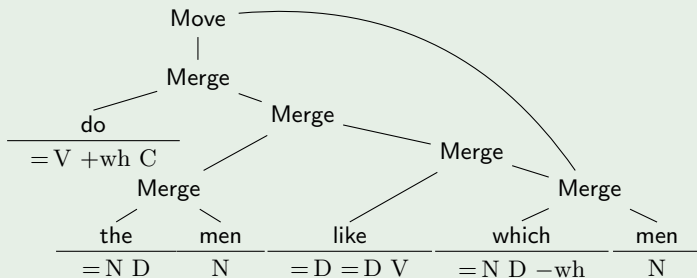
# Example Transduction

## Example



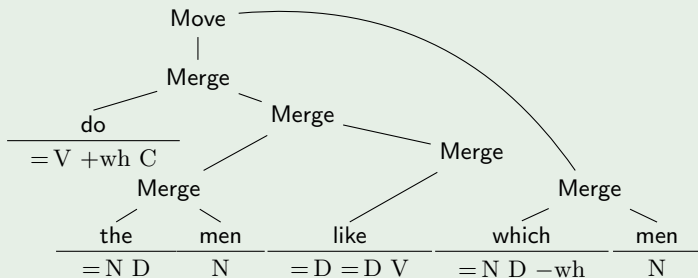
# Example Transduction

## Example



# Example Transduction

## Example



# The Basic Idea

- We now have a FO-definable theory of Minimalist derivations and a simple MSO transduction to derived trees.
- But there is wiggle room: MGs generate MCFLs, and **MCFL = str(MSO-TT(REG))**.
- So we can change certain parameters in the definitions, as long as MSO-definability is preserved  
⇒ **parametric template to create new variants of Move**

# Parameters of Move

The variants of Move discussed in the syntactic literature vary along several dimensions:

- Possible landing sites: raising, lowering, sideways
- Size of moved constituent: phrase, head, pied-piped phrase
- Visibility: overt, covert
- Directionality: left, right

## Loci of Parameters

Parameter	Locus
landing site	definition of occurrence
size	transduction
visibility	transduction
directionality	transduction

# Replacing Proper Dominance

## Reminder: Definition of Occurrence

$occ_i(l)$  is the unique node  $m$  of  $t$  labeled Move such that

- $m$  is associated to  $+f_i$ , and
- $m$  **properly dominates**  $occ_{i-1}$ , and
- there is no node  $n$  in  $t$  such that
  - $n$  is associated to  $+f_i$ , and
  - $n$  properly dominates  $occ_{i-1}$ , and
  - $n$  is properly dominated by  $m$ .

## Alternative Instantiations

### Relation

inverse proper dominance

proper dominance across at most 1 slice

slice containment

slice containment restricted to wh-phrases

### Movement Type

lowering

antilocal raising

sideways

wh-clustering

# Size of Moved Constituent

## Reminder: The Transduction Formula

$$x \blacktriangleleft y \leftrightarrow x \triangleleft y \vee \exists l[f\text{-occ}(x, l) \wedge \text{sliceroot}(y, l)]$$

## Alternative Instantiations

### Formula

$$y \approx l$$

$$\exists l'[\text{sliceroot}(y, l') \wedge \text{selects}(l', l)]$$

### Movement Type

head movement

pied-piping



## Further Observations

- With respect to directionality, all movement types can be **replaced by a combination of raising and lowering** (but new lexical items might be needed to furnish extra landing sites).
- In most cases, **strong generative capacity is increased** (e.g. lowering makes it possible to generate any given TAL with  $X'$ -like trees).
- Many MSO-definable relations do not yield useful movement types (e.g. all reflexive and all symmetric relations).

# Conclusion

## What was Accomplished?

- MSO definition of MGs as derivation tree languages with a mapping to derived trees.
- Definitions provide a parameterized template that can easily be tuned to create new movement types without increasing weak generative capacity.

## Why Should You Care?

- Combined with the results of Graf (2011) and Kobele (2011), we now have a general system for adding constraints and movement types to MGs  $\Rightarrow$  extremely flexible framework (just about anything from the literature can be incorporated)
- New movement types make it possible to emulate other formalisms  $\Rightarrow$  resource sharing, new perspectives

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